Fertilizer Transportation Sampling

International Fertilizer Industry Association (IFA)
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Fertilizer Transportation Sampling (Truck, Railcar, Bulk Container, Ship / Barge Hold)

Introduction

With the acceleration of global fertilizer trade, IFA’s diverse membership has experienced an increasing number of contractual disputes due to the use of different methods and procedures to sample and analyze international product shipments at different points in the supply chain. In a member-driven initiative, a broad-based international task force was formed to address this matter.

Accurate and representative sampling is a challenging operation that requires both knowledge of the product as well as the correct application of the sampling process. Sampling procedures must be applied in a strict manner by trained personnel with prior sampling experience. Moreover, a standardized approach must be adopted irrespective of the sampling location, shipment mass or volume, or commodity.

Transportation sampling of material from loaded trucks, railcars, bulk containers, and barge is a common request

Mechanical Probe Sampling

For operating sites where the preferred full stream mechanical sampling systems are not available, stationary bulk materials from trucks, railcars, bulk containers or barges can be sampled by means of a mechanical probe sampling system.

Mechanical probe sampling systems result in more accurate, representational results than manual “car top” sampling.

Mechanical probe sampling systems have advantages over manual techniques:

1. Well-designed mechanical probe systems allow for a more reliable means to extract and collect primary increments from a vertical column at desired point and depth;
2. This procedure reduces health and safety risk to sampling personnel as it avoids manual sampling from top of loaded trucks, railcars, containers or barges.

It is essential that mechanical sampling systems be regularly inspected and audited to ensure correct sampling and compliance to original design and applicable standards.

Manual Sampling

In the absence of a mechanical sampling system, manual sampling may be carried out on fertilizer material being transported by truck, railcar, bulk container or barge. Table 1 lists various industry manual sampling methods and procedures for transportation sampling. Comparably, the methods listed follow the same principle with basic, minimum conditions that must be fulfilled to ensure that a sample of fertilizer fairly represents the lot of fertilizer from which the sample is taken. These minimum conditions are as follows:
A. Determine the purpose for which the sample is required and determine the characteristics of the material, i.e., its estimated quality, maximum particle size, homogeneity, etc.;

B. Determine the number of sampling units for the shipment. The number of sampling units should be taken as the square root of the number of units (packaged product) or the square root of 4 times the total tonnage (bulk) present in the lot or shipment, with 10 units being the minimum;

C. Select at random 10 sampling units to be sampled. Incremental samples shall be taken from the 10 selected sampling units;

D. Use a standard sampling pattern so that each increment represents an approximate equal fraction of the whole;

E. Obtain a sample that consists of approximately equal portions (increments) drawn from each sample location;

F. Obtain a sample of a sufficient mass or volume for the required analyses.

For industry quality control purposes, a "lot" shall be represented by the quantity of a given product made during a specified time period, in storage at a single location, or shipped from a single production point.

When transporting a "lot" e.g. in multiple railcars, trucks and barges a sampling unit can be regarded as a single rail car, a separate hold or an imaginary division of the surface of the product. Ensure that a minimum of 10 sampling units are considered and define the sampling scheme for the minimum number of increments to be taken from each unit. Example: Up to 100 railcars the minimum number of railcars to be sampled would be ten, with increments taken from each selected railcar.

Sampling from Ships Holds – There may be a request or need to sample product in a static condition from a ship or vessel's hold. Due to the typical size of a vessel hold it is recommended that each hold be sampled as an individual lot, obtaining a minimum of 10 equally distributed increments from randomly selected sampling units in each hold.

For the sampling of vessel's with product in a dynamic condition refer to “IFA Recommended Best Practices for the Sampling of Dry Bulk Fertilizer Shipments”.

Experience has demonstrated that sampling methods (and samples), all other conditions being equal, are more reliable whenever a larger number of (unbiased) increments are collected.

It should be noted that, while the basic sampling methods outlined are comparable in principle, due care must be followed in utilizing proper sampling equipment / apparatus for the material being sampled. Studies have concluded that the double tube trier (spear) is the recommended apparatus for probe sampling; however, the dimensions of the trier have to be appropriate to the characteristics of the sample portion and to the particle size of the fertilizer. Increments collected should be stored immediately in moisture-impervious containers (if moisture is a concern / specification), but always in a container capable of preserving the integrity of the collected increments.

Conditions such as segregation, heterogeneity, stratification, contamination, etc. must be considered if bias is to be avoided and if sampling and sample preparation variance are to be minimized.

Manual sampling of the type described above (from loaded trucks, cars, bulk containers, vessel holds, etc.) does not satisfy the minimum requirements for probability sampling, and as such should not be used to draw statistical inferences such as precision, standard error, or bias.

For more reliable methods that provide probability samples, it is recommended that, whenever possible, sample increments should be collected during loading or during material transport, i.e., while the material is in movement.
During any sampling operation, consideration must be given to conditions that help to minimize health and safety risks to personnel.

**Disclaimer:**

*Manual sampling from the top of loaded Truck, Railcar or Bulk Container (car top) is a dangerous activity and should only be carried out from a safe location such as loading rack or platform.*

*Car top sampling should only be performed in locations and facilities where such an activity is permitted in accordance with the local facilities health and safety rules.*

*While recognizing that car top sampling is common practice in many locations, IFA does not accept any responsibility for any incident that may result from the execution of such sampling activities, nor for any of the other activities described in this paper.*
<table>
<thead>
<tr>
<th>Standard</th>
<th>Number of increments</th>
<th>Mass of increment</th>
<th>Sampling place / depth of probe</th>
<th>Apparatus</th>
<th>Sample container</th>
<th>Sample Division</th>
<th>Remarks / Region in use</th>
</tr>
</thead>
<tbody>
<tr>
<td>AOAC 929.01</td>
<td>10</td>
<td>Not defined</td>
<td>Deep probing form surface</td>
<td>Double tube triers “Missouri” “Missouri D” “552 Grain”</td>
<td>Airtight container</td>
<td>riffle divider</td>
<td>Internationally recognized.</td>
</tr>
<tr>
<td>ISO 8633:1992</td>
<td>10, up to 5 mt x 20</td>
<td>Minimum mass of increment as per ISO/TR 7553</td>
<td>From surface</td>
<td>Flat-bottomed shovel or scoop with vertical sides. Spear can be used provided it can collect increments more than the minimum mass and is appropriate for sample particle size</td>
<td>Sealable, airtight container</td>
<td>riffle divider</td>
<td>Internationally recognized.</td>
</tr>
<tr>
<td>GOST 21560.0</td>
<td>&lt; 5 mt – 7 increments</td>
<td>no less than 200g</td>
<td>From Surface</td>
<td>Clean and dry jar with lid, or double plastic bag which should be sealed</td>
<td>Rotating divider or riffle divider, average sample 1 to 2.5 kg</td>
<td>Russia and other FSU countries</td>
<td></td>
</tr>
<tr>
<td>Railcars (covered, side opened)</td>
<td>&gt; 5 mt – 10 increments</td>
<td>36 increments</td>
<td>inside of railcar</td>
<td>Scoop or Single Tube Trier.</td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>TFI, Fertiliser sampling and analytical methods, 4th Edition</td>
<td>Trucks, opened railcars</td>
<td>10 increments</td>
<td>Not defined</td>
<td>From surface Not less 4 feet (1.2 m) depth</td>
<td>Double tube triers “Missouri” “Missouri D” “552 Grain”</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Multi-Compartment Trucks</td>
<td>10 per each compartment</td>
<td></td>
<td></td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>Hopper cars</td>
<td>3-4 hatches – 4 probes per hatch</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>&gt;4 hatches – 2 probes per hatch</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Standard</td>
<td>Number of increments</td>
<td>Mass of increment</td>
<td>Sampling place / depth of probe</td>
<td>Apparatus</td>
<td>Sample container</td>
<td>Sample Division</td>
<td>Remarks / Region in use</td>
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</tr>
<tr>
<td>KEBS Kenya Bureau of Standards</td>
<td>10</td>
<td>Not defined</td>
<td>From surface “Draw to the maximum possible depth”</td>
<td>Not defined</td>
<td>Airtight container</td>
<td>Not defined</td>
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<tr>
<td>Sampling of Fertilizers for the purpose of PVOC Kenya February 2009</td>
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<tr>
<td>FAI, The Fertiliser (control) order 1985 (as amended up to June 2006)</td>
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<td></td>
<td></td>
<td>Clean, dry and airtight glass or screwed hard polythene bottle 400 g capacity or thick gauged polythene bag</td>
<td></td>
<td></td>
<td>Portions should be mixed as possible by suitable means</td>
</tr>
<tr>
<td>Vessel’s Holds / hatches</td>
<td>10 - 15 increments from each hatch and from different depths and different points during unloading operations</td>
<td>Not defined</td>
<td>Deep probe from surface</td>
<td>Deep probe from surface</td>
<td></td>
<td></td>
<td>India</td>
</tr>
<tr>
<td>Trucks</td>
<td>10 vertical probes, as per scheme</td>
<td>Not defined</td>
<td>Deep probe from surface</td>
<td>Deep probe from surface</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>AFPC VI.1</td>
<td></td>
<td></td>
<td></td>
<td>Missouri trier Preferred tools 1.5 m length, ¾ in in diameter</td>
<td></td>
<td></td>
<td>USA, Internationally</td>
</tr>
<tr>
<td>Trucks and Hopper cars, Railcars</td>
<td></td>
<td></td>
<td></td>
<td>Missouri trier Preferred tools 1.5 m length, ¾ in in diameter</td>
<td></td>
<td></td>
<td>USA, Internationally</td>
</tr>
<tr>
<td>Ship Hold</td>
<td></td>
<td></td>
<td></td>
<td>Missouri trier Preferred tools 1.5 m length, ¾ in in diameter</td>
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<td>USA, Internationally</td>
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<tr>
<td></td>
<td></td>
<td></td>
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<td>Missouri trier Preferred tools 1.5 m length, ¾ in in diameter</td>
<td></td>
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<td>USA, Internationally</td>
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</tbody>
</table>
Sampling Schemes

Figure 1. ISO sampling pattern.

Figure 2. TFI sampling pattern.

Figure 3. Fertilizer Control Order (FCO) sampling pattern.

Figure 4. TFI sampling pattern – Hatch cover.

Figure 5. AOAC sampling plan – Hopper cars.

Sampling Apparatus

Figure 6. Flat-bottomed shovel or scoop with vertical sides.

Figure 7. Double tube trier.

Figure 8. Transfer of core sample from Missouri “D” tube into intermediate container.

Note: A slotted double tube trier (Figure 7) is the recommended apparatus for probe sampling.
Sampling Apparatus

**Figure 9.** Example of Mechanical Probe Sampler.

**Figure 10.** Example of Mechanical Probe Sampler.